

Solving Minimum Cut Cover with Adelman-Lipton model

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Abstract: Adleman proved that deoxyribonucleic acid (DNA) strands could be used towards calculating solutions to an instance of the Hamiltonian path problem (HPP). Lipton the next NP problem with this technique. In this paper, we use this model for developing a new DNA algorithm to solve minimum cut cover problem (MCCP). In spite of the NP-hardness of minimum Cut Cover problem (MCCP) our DNA procedures is done in a polynomial time.

Keywords: DNA computing, minimum Cut Cover problem.

I. INTRODUCTION

DNA computing has two very powerful features, Watson-Crick complementarity and massive parallelism. It is clear we cannot solve NP problems with silicon-based computer, But DNA computing provides powerful feature which can solve those problems in polynomial steps. Adleman [1] solved Hamiltonian path problem of size n . That is the first work for DNA computing. Lipton [5] solved the second NP hard problem with this algorithm. Some other NP-hard problems that have been solved [6-21].

In this paper, the DNA operations proposed by Adleman [1] and Lipton [1] are used to solve minimum independent dominating problem.

For a given Graph $G = (V, E)$ we want to find a subset $V' \subset V$ with minimum cardinality such that for all $u \in V - V'$ there is a $v \in V'$ for which $(u, v) \in E$. And also, no two vertices in V' are joined by an edge in E .

The rest of this paper is organized as follows. In Section 2, the Adleman-Lipton model is introduced in detail. Section 3 we will present a DNA algorithm for solving the minimum independent dominating set problem and the complexity of the proposed algorithm is described. We give conclusions in Section 4.

II. PAGE LAYOUT

Bio-molecular computers work at the molecular level. Since biological and mathematical operations have some similarities, DNA, the genetic material that encodes the living organisms, is stable and predictable in its reactions and can be used to encode information for mathematical problems. DNA algorithms typically solve problems by initially assembling large data sets as input and then eliminating undesirable solutions [14].

A DNA (deoxyribonucleic acid) is a polymer, which is strung together from monomers called deoxyribose nucleotides [14]. Distinct nucleotides are detected only with their bases [13].

Those bases are adenine (A), guanine (G), cytosine (C), and thymine (T). Two strands of DNA can form (under appropriate conditions) a double strand, if the respective bases are the Watson-Crick complements of each other, i.e., A matches T and C Matches G; also 3'- end matches 5'- end. For example, strands 5'-ACCGGATGTCA-3' and 3'-TGGCCTACAGT-5' can form a double strand. We also call them as the complementary strand of each other [12].

The length of a single DNA strand is the number of nucleotides comprising the single strand. Thus, if a single DNA strand includes 20 nucleotides, it is called a 20 mer. The length of a double strand (where each nucleotide is base paired) is counted in the number of base pairs [4]. Thus, if we make a double strand from two single strands of length 20 mer, then the length of the double strand is 20 base pairs, also written as 20 bp for more discussion of the relevant biological background, refer to [3]. The DNA operations proposed by Adleman and Lipton [2] are described below.

A (test) tube is a set of molecules of DNA (i.e. a multi-set of finite strings over the alphabet {A, C, G, T}). The following operations perform on tubes [2]:

- (1) *Merge* (T_1, T_2): for two given test tubes T_1, T_2 it stores the union $T_1 \cup T_2$ in T_1 and leaves T_2 empty [4];
- (2) *Copy* (T_1, T_2): for a given test tube T_1 it produces a test tube T_2 with the same contents as T_1 [2];
- (3) *Detect* (T): Given a test tube T it outputs "yes" if T contains at least one strand, otherwise, outputs "no" [2];
- (4) *Separation* (T_1, X, T_2): for a given test tube T_1 and a given set of strings X it removes all single strands containing a string in X from T_1 , and produces a test tube T_2 with the removed strands [3];
- (5) *Selection* (T_1, L, T_2): for a, given test tube T_1 and a given integer L it removes all strands with length L from T_1 , and produces a test tube T_2 with the removed strands [8];

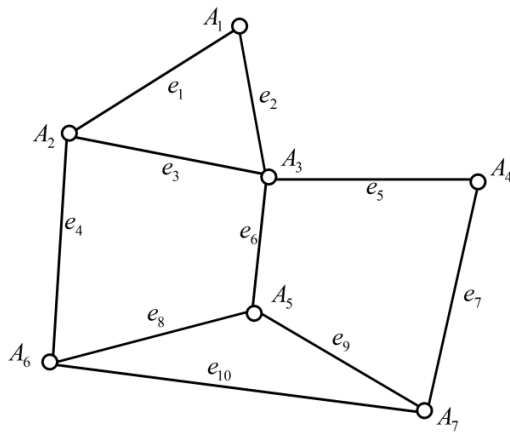


Fig. 1. Graph G.

(6) *Cleavage* ($T, \sigma_0\sigma_1$): for a, given test tube T and a string of two (specified) symbols $\sigma_0\sigma_1$ it cuts each double strand containing $\begin{bmatrix} \sigma_0\sigma_1 \\ \sigma_0\sigma_1 \end{bmatrix}$ in T into two double strands as follows:

$$\begin{bmatrix} \alpha_0\sigma_0\sigma_1\beta_0 \\ \alpha_1\sigma_0\sigma_1\beta_1 \end{bmatrix} \Rightarrow \begin{bmatrix} \alpha_0\sigma_0 \\ \alpha_1\sigma_0 \end{bmatrix}; \begin{bmatrix} \sigma_1\beta_0 \\ \sigma_1\beta_1 \end{bmatrix}$$

(7) *Annealing* (T): for a, given test tube T it produces all feasible double strands in T . The produced double strands are still stored in T after Annealing [6];

(8) *Denaturation* (T): for a, given test tube T it dissociates each double strand in T into two single strands [7];

(9) *Discard* (T): for a, given test tube T it discards the tube T [11];

(10) *Append* (T, Z): for a, given test tube T and a given short DNA singled strand Z it appends Z onto the end of every strand in the tube T [12];

(11) *Read* (T): for a given tube T , the operation is used to describe a single molecule, which is contained in the tube T . Even if T contains many different molecules each encoding a different set of bases, the operation can give an explicit description of exactly one of them [13].

Since these eleven manipulations are implemented with a constant number of biological steps for DNA strands, we assume that the complexity of each manipulation is $O(1)$ steps [14].

III. SOLVING MIDSP BY ADLEMAN-LIPTON MODEL

Let $G=(V,E)$ be an undirected graph with the set of vertices being $V=\{A_k | k=1,2,\dots,m\}$ and the set of edges being $E=\{e_i | i=1,2,\dots,n\}$ [3]. Let $|E|=d$. In the following, the symbols $0,1,2,\#,X,Y,A_k,B_j,C_j (k=1,2,\dots,m, j=1,2,\dots,m)$ denote distinct DNA singled strands with same length, say 10-mer. And $||\cdot||$ denotes the length of the DNA singled strand. Obviously, the length of the DNA singled strands greatly depends on the size of the problem involved in

order to distinguish all above symbols and to avoid hairpin formation [3].

Tubes P and Q are defined as follows:

Let

$P = \{j, X, A_j\#, \#B_n, A_k B_{k-1}, Y | k=1,2,\dots,n, j=1,2,\dots,n\}$ and

$Q = \{\#, B_k j A_k | k=1,2,\dots,n, j=1,2,\dots,n\}$ We design the following algorithm to solve the minimum independent dominating set problem and give the corresponding DNA operations as follows:

IV. PRODUCE EACH POSSIBLE SUBSET FROM E

For a graph with n vertices, each possible C of vertices is represented by an n -digit number in base W . For example, for graph 1 we can represent

$C = \{V_1 = \{A_1, A_2, A_3\}, V_2 = \{A_5, A_6, A_7\}\}$ as 2220111

and show $C = \{V_1 = \{A_1, A_3, A_4\}, V_2 = \{A_5, A_6, A_7\}\}$ as 2221101, in which number j in i -th element shows that

the vertices A_i is in the j -th subset, and if $j=0$ it means that this vertex doesn't exist in any of the subsets.

In this way, we transform all possible collection C in an n -vertex graph into an ensemble of all n -digit in base W numbers. We call this the data pool.

(1-1) *Merge* (P, Q);

(1-2) *Annealing* (P);

(1-3) *Denaturation* (P);

(1-4) *Separation* ($P, \{A_i\#, T_{mp}$);

(1-5) *Discard* (P);

(1-6) *Separation* ($T_{mp}, \{\#B_n\}, P$);

After above six steps of manipulation [15], singled strands in tube P will encode all W^n collection C in the form of n -digit base W numbers. For example, for the graph in Fig. 1 with $n=7$ we have, e.g. the singled strand $\#B_7 2A_7 B_6 2A_6 B_5 2A_5 B_4 0A_4 B_3 1A_3 B_2 1A_2 B_1 1A_1 \#$

Which denotes the subset $C = \{V_1 = \{A_1, A_2, A_3\}, V_2 = \{A_5, A_6, A_7\}\}$ corresponding to the number 2220111 in base W . This operation can be finished in $O(1)$ steps since each manipulation above works in $O(1)$ steps.

V. ELIMINATING INVALID SUBSETS

In definition of problem, no two vertices in V' are joined by an edge in E . It means if for each $(u,v) \in E, u \in V'$ and $v \in V'$, those subsets are invalid. For example,

$V_1 = \{A_1, A_5, A_6, A_7\}$ is an invalid subset because there is an edge between A_1 -- A_6 .

For $i = 1$ to $d = n$

For $d = 1$ to $d = n$

if $(A_d, A_j) \in E$

(3-1) Separation $(P, \{B_i 1A_d\}, T_1)$

(3-2) Separation $(T_1, \{B_i 1A_i\}, T_2)$

(3-3) Merge (P, T_1)

(3-4) Discard (T_2)

Endif

End for

End for

$B_6 1A_6, B_1 1A_1$ mean both of vertices 1 and 6 are in this subset.

If we have an edge between vertices 1 and 6, then this an invalid subset according to definition of the problem.

In this part, we remove subsets which have an edge among their vertices.

In the second part, we will remove those subsets that cannot meet this condition, for all $u \in V - V'$ there is a $u \in V'$ for which $(u, v) \in E$. We assume, we have a strand which contains $B_6 0A_6$. It means $6 \in V - V'$ then we are looking for those strands which contain $B_i 0A_i$ and $(6, i) \in E$.

$B_i 0A_i$ means i-th vertex belong to V' .

For $i = 1$ to $d = n$

(3-1) Separation $(P, \{B_i 0A_d\}, T_1)$

For $d = 1$ to $d = n$

if $(A_d, A_j) \in E$

(3-2) Separation $(T_1, \{B_i 1A_i\}, T_2)$

(3-3) Merge (T_3, T_2)

(3-4) Discard (T_2)

Endif

End for

(3-5) Merge (P, T_3)

(3-6) Discard (T_2)

End for

It is obvious those algorithms will terminate in $O(n^2)$.

VI. CALCULATE THE CARDINALITY EACH SUBSETS

The cardinality of each subset is equal to number of vertices in V' . To count the number of vertices in V' we

need to count $B_i 1A_i, i = 1, 2, \dots, n$. For each strand contain

$B_i 1A_i, i = 1, 2, \dots, n$ we will add # to the end of those strands.

For $i = 1$ to $d = n$

(3-1) Separation $(P, \{B_i 1A_d\}, T_1)$

(3-2) Append $(T_1, \#)$

(3-3) Merge (P, T_1)

End for

We have n iterations, then this algorithm will terminate at $O(n)$.

VII. FIND THE SUBSET WITH MAXIMUM CARDINALITY

For example, we have V' with n vertices, then the strands of that subsets contain $\frac{\#\dots\#}{n}$.

If we found some strands which contain $\frac{\#\dots\#}{n}$, those strands will be our solution. Otherwise we will continue with $\frac{\#\dots\#}{n-1}$ and $\frac{\#\dots\#}{n-2}, \dots$.

For $i = n$ to $i = 1$

(2-1) Separation $(P, \{\frac{\#\dots\#}{i}\}, T_1)$

if T_1 is not Empty

(2-2) Break

End if

End for

VIII. CONCLUSION

In this paper, we proposed new polynomial algorithm for one of NP-Hard Problems. As you can see this algorithm will finish in $O(n^2)$

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